Exploratory Training: When Trainers Learn

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ABSTRACT

Data systems often present examples and solicit labels from users to learn a target concept in supervised to semi-supervised learning. This selection of examples could be even done in an active fashion i.e., active learning. Current systems assume that users always provide correct labeling with potentially a fixed and small chance of mistake. In several settings, users may have to explore and learn about the underlying data to label examples correctly, particularly for complex target concepts and models. For example, to provide accurate labeling for a model of detecting noisy or abnormal values, users might need to investigate the underlying data to understand typical and clean values in the data. As users gradually learn about the target concept and data, they may revise their labeling strategies. Due to the significance and non-stationarity of errors in this setting, current systems may use incorrect labels and learn inaccurate models from the users. We report preliminary results for a user study over real-world datasets on modeling human learning during training the system and layout the next steps in this investigation.

CCS CONCEPTS

• **Information systems → Data cleaning**; *Data analytics*;
• **Human-centered computing → User models**.

KEYWORDS

data exploration, human in loop, human learning, hypothesis-testing model, bayesian model, functional dependencies, collaborative learning

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1 INTRODUCTION

AI Systems often are dependent upon labels from humans to learn a model and hence present training examples to them for labeling, which could be done in an active fashion [1, 4, 7, 12, 13]. For instance, data systems often learn data quality constraints and models by presenting chosen examples to the human experts [7]. In each interaction, the system can select an example for labeling based on the training data already given by the user and the effectiveness of the current model. This approach improves the flexibility of choosing examples and may significantly reduce the training data [1].

Due to the sheer volume and complexity of data, data labeling and model training over large datasets may be interactive and exploratory. Users interactively inspect the data to improve their knowledge, refine their inputs, and revise their hypotheses about the target insight based on the results of preceding interactions. Thus, to label examples correctly, users often have to learn about the underlying data, particularly for complex models. Even for providing accurate labeling for a model of detecting noisy or abnormal values, users may need to explore the data to understand typical and clean values. It is often vital for users to train accurate models fast.

As users explore and interact with the data, their knowledge about the data and the target concept evolves. Thus, they may modify their labeling and training strategies. It is known that human learning in interactive settings is highly non-stationary [3, 5, 10, 11, 16, 17]. For example, they may have a prior belief (distribution) about the properties of positive or negative examples for the target concept based on their background information and expertise. They may continually and gradually revise their belief and in turn labeling strategies after observing new data items, and settle on a relatively fixed strategy after gaining sufficient knowledge about their actions and environment [3, 5, 9, 11, 16]. Due to the huge volume of the data and complexity of the target insight, this learning process may take a relatively long time. Thus, it is challenging for the system to understand or find reliable users' inputs in the interaction to learn an effective model for their target concepts.

Nonetheless, most systems assume that users have perfect knowledge about the target insight and underlying data [1, 4, 6].. Only few works drop the assumption that users provide reliable feedback or training data with potentially a very small and fixed amount of noise [14, 15]. Indeed, as user knowledge about the data may significantly change during the analysis, it is not clear which inputs are sufficiently reliable for predicting the target insights. Due to the significance and non-stationarity of errors, current systems will use incorrect labels and learn inaccurate models. Moreover, current systems use fixed, stationary, and/or pretrained models of user exploration and training process to build a model for the target concept [1, 8, 18]. Stationary learners are unduly biased to the initial observations and fail to adapt subsequently.

As the first step to realize the vision of fast and effective exploratory training, we report our user studies on modeling human learning over real-world datasets for a data cleaning task. Such a model will enable designing algorithms that learn the target concepts effectively and quickly in exploratory training. We show that human learning in this context accurately follow the well-known Bayesian learning model, which has also been observed to effectively model human learning in other domains, such as economics and image classification [16, 17].

2 USER LEARNING SCHEMES

Human learning is generally categorized as *model-free*, i.e., reinforcement based, and *model-based* learning, i.e., belief learning [5, 16, 17]. In model-free learning, users modify their strategies by directly reinforcing actions. In model-based one, they form hypotheses about the data and actions of the system and update their strategies given the success of their preceding predictions [16, 17].

In the type of interaction we investigate, the system presents a set of unlabeled examples to the user. It is reasonable to assume that the user has some initial hypotheses about the target concept, which they may repeatedly revise after viewing the presented examples in each interaction. Also, in our setting, systems usually interact with users who often have some initial models of the domain. Thus, model-based learning schemes are natural choices for the cases where users are training a system interactively [5, 16, 17].

We focus on two prominent model-based learning methods: *hypothesis testing* and *Bayesian learning* [16, 17].

In **hypothesis testing**, the user randomly selects a hypothesis according to how well it explains the observed data and uses it to label examples. For instance, if they view sufficiently many examples with value "NaN" in the interaction, they conclude that "NaN" is not noise and is used by the database designer to represent unknown values. The user frequently evaluates the performance of her hypotheses, rejects the current one if it does not explain sufficient amount of recent data with some tolerance, and picks another hypothesis randomly based on its relative performance.

In **Bayesian learning**, the user starts with a prior about different models for the target concept [17]. They then performs Bayesian updating on the probability of choosing each hypothesis given the examples presented to them in each interaction. They picks a hypothesis according to these probabilities and labels examples accordingly.

3 EMPIRICAL STUDY

In this paper, we focus on modeling human learning in the context of data quality constraints and discovering violations of those rules. Our work is focused towards modeling the learning process of humans in rule discovery with two models: *Bayesian learning* and *Learning based on hypothesis testing*. We address our research questions by analyzing how the user iteratively navigates the space of applicable functional dependencies (FDs) in several scenarios.

We first define functional dependencies and their violations, we then describe the setup, including the process of interactively labeling data, and conclude with the results.

3.1 Task: Detecting FD Violations

A **functional dependency (FD)** is a pattern that explains how attributes in a dataset relate to and are dependent on one another. For example, in datasets containing addresses or other location data, an address's city and ZIP code determine the state that location is in. Another example is a person's SSN determining a range of personally identifiable information, such as the person's name, date of birth, and address. These examples can be represented as $(city, zip) \Rightarrow state$ and $SSN \Rightarrow (name, dob, address)$, respectively.

If a tuple has one or more cell(s) with values that do not align with the rest of the dataset w.r.t. an FD, then the tuple *violates the FD* or is referred to as an *exception to the FD*.

3.2 Experimental Setting

Our empirical study involved a group of 20 students at Oregon State University with different background in Computer Science. We implemented a user interface that refreshes user on FDs and their violations, tests their knowledge, and presents samples iteratively for interaction and rule specification.

3.2.1 Datasets. We use synthetic variations of two real-world datasets. **AIRPORT** describes airports, heliports, and seaplane bases throughout the U.S. state of Alaska, while **OMDB** (Open Movie Database) contains information about English-language movies and TV shows. The exact attributes present in each dataset vary slightly by scenario. Each scenario has around 200 tuples. We utilized 5 configurations of these two datasets which are shown in Table 1.

The target FD is the one with fewest violations in the overall dataset whereas alternative hypothesis is what we believe participants may initially believe should hold over the dataset with fewest exceptions, given the schema and an initial look at the data.

#	Domain	Attributes	FD
1	Airport	facilityname type manager	Target: *(facilityname, type)* ⇒ *manager* Alternative: *facilityname* ⇒ *(type, manager)*
2	Airport	sitenumber facilityname owner manager	Target: *sitenumber* ⇒ *(facilityname, owner, manager)* Alternative: *facilityname* ⇒ *(sitenumber, owner, manager)*
3	Airport	facilityname owner manager	Target: *manager* ⇒ *owner* Alternative: *facilityname* ⇒ *(owner, manager)*
4	OMDB	title year genre type	Target: *(title, year)* ⇒ *(type, genre)* Alternative: *title* ⇒ *(year, type, genre)*
5	OMDB	title rating type	Target: *rating* ⇒ *type* Alternative: *title* ⇒ *(rating, type)*

Table 1: Scenarios used in the empirical study

3.2.2 Introducing Violations. The dataset exposed to the users is prepared by introducing violations in the clean one. We introduce violations with an error generation tool that scrambles values w.r.t. the target FD [2]. An m:n *violation ratio* is the proportion of m target hypothesis violations and n alternative hypothesis violations. This ratio help to reveal if the learning process depends on the quantity of violations in the samples.

3.2.3 Interactions. In the beginning, the user is presented with the dataset schema and asked what they believe is the FD that holds over the dataset with the fewest exceptions. In each iteration, a random sample of data from the dataset with violations is shown to the user. The user is allowed to mark any violations of their hypothesized FD, i.e., the one that they believe to hold with fewest exceptions within that sample. After marking violations, they confirm or modify their hypothesized FD. The user must interact for at least 9 iterations for completion and can continue up to 15 iterations. The number of interaction depends on the user's learning and confidence over the hypothesized FD.

To avoid an high cognitive load on our participants, we focus on datasets with few attributes. However, they are complex enough to make it hard to immediately figure out the underlying rule without having to interact with the data.

3.3 Model Configuration

The aim of both of our models (Bayesian and hypothesis testing) is to predict the user specified hypothesis based on the labeling provided by the user till the current iteration. We evaluate both models in terms of **Mean Reciprocal Rank (MRR)** for an exact match between the model's top-k suggestions and the participant's submitted hypothesis.

To evaluate which window for top suggestions (k) better models user behavior, we compare each model's performance with three values of k (1, 3, 5), which corresponds with how many FDs are output by the model in each iteration. We therefore refer to our Bayesian and hypothesis testing model configurations as *BAYES-k* and *HP-k*. We also compare each model to its respective variants that consider subset and superset relationships in the model's top suggestions rather than only a perfect FD match. In our results, models with this configuration include a "+" in their names.

3.4 Experimental Results

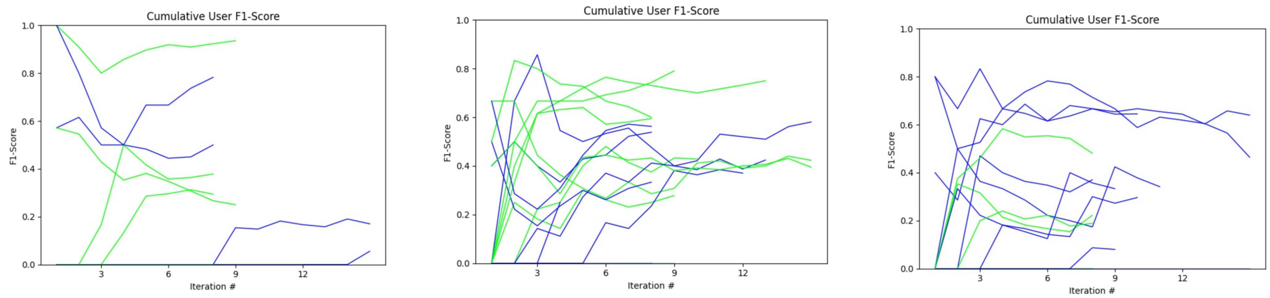
3.4.1 Measuring Learning. To quantify the user learning, we first review the extent to which the f_1-score of the user's hypothesis changes between iterations.

Scenario #	Average change in f_1-score
1	0.1144
2	0.3280
3	0.2301
4	0.2843
5	0.1767

Table 2: Average f_1-score change between any two rounds of user labeling, grouped by scenario

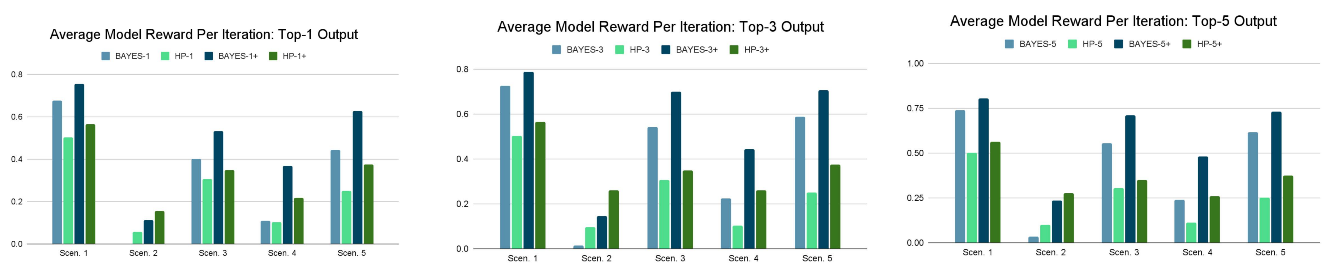
The average change in f_1-score is positive and relatively large as shown in Table 2. This suggests that changes in the user's hypothesis from iteration to iteration are likely not due to simple noise and error, but is rather due to the user actually learning and updating their hypothesis.

Next, we analyze the users' labeling activity across each interaction to evaluate how their hypothesis-forming process evolves as they are exposed to more data and continue interacting with them. The result in **Figure 1** reveals that, in general, the user's ability, to detect and mark violations of the target FD, improves as the interaction proceeds. We report plots for three scenarios in the Figure, scenarios 4 and 5 show similar trends.



(a) Scenario 1 **(b) Scenario 2** **(c) Scenario 3**

Figure 1: Each participant's change in labeling performance, measured by f1-score. Blue lines represent interactions with a 3:1 violation ratio. Green lines represent interactions with a 3:2 violation ratio



(a) k=1 **(b) k=3** **(c) k=5**

Figure 2: Average reward per iteration for each learning model with k

3.4.2 Evaluating Learning Models. Now that we can see user performance improve over time, we turn to our models to measure their ability to replicate the users' hypotheses over the course of the interaction. For this we used MRR which is referred to as model reward in **Figure 2**.

In comparison to the hypothesis testing model, our Bayesian model acquires better modeling performance with higher reward per iteration on average, in almost all the scenarios and value of k (**Figure 2**). As the value of k increases, the performance of all model configurations improve as expected, as this gives the model more opportunities to return an FD that matches a user's hypothesis.

Our empirical results show that as humans interact with more data, their ability to accurately label violations in the data and specify qualitative hypothesis of data rule increases. This is due to the user iteratively learning and refining their understanding of the data. Furthermore, the user's learning process follows a probabilistic Bayesian learning model when the model's measure of success is its ability to perfectly match the user's hypothesis. However, when the measure of success is loosened to accept variations of the user's hypothesis as viable matches, the hypothesis testing model also mimics user behavior fairly well.

4 LIMITATIONS & CHALLENGES

Generalizable Modeling of Human Learning. To validate further our assumptions on the model of human learning, we plan to perform additional user studies on other tasks like classification. We also plan to investigate the characteristics of the target concept, e.g., its difficulty, that may cause users to prefer certain learning method(s) or hyper-parameters, e.g., tolerance in hypothesis testing.

Collaborate With Learning Humans. We plan to design algorithms to accurately learn the target concept from a learning trainer. This approach views exploratory training as the interactive collaboration user and data/AI system, for achieving the common goal of learning users' desired concept using the fewest possible interactions.

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