



Assessing Multiple Imputation of Missing Values for Robust Analysis of Telehealth Kiosk Data

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Introduction

- **Telehealth** allows the distribution of health-related services.
- Promising avenue for prevention, and remote diagnosis and monitoring of diseases.
- Can be a solution when **access** to care is **restricted**.





Bodyo AiPod

- Stand-alone **telehealth** kiosk.
- Measures **27 health indicators** in 6 minutes.
- 4 sensors collect information :
 - a scale
 - a **body composition** sensor
 - an **oximeter**
 - a **blood pressure** sensor





Deploying the AiPod

- In non-clinical contexts **sensors may fail**, leading to incomplete data.
- If one sensor fails **all measures** collected by the sensor go missing.
- We cannot afford to **discard** incomplete observations.

Problem: How to deal with missing data?





Working with missing data

- We investigate two ways to deal with missing data:
 - Imputation schemes to fill the missing values.
 - A set approach that avoids imputation.





Imputation of missing values





Imputation schemes

- We still want to keep observations with missing values.
- Imputation schemes allow to fill missing values.
- Imputation needs to preserve the integrity of the original data.





Multiple Imputation with Denoising Autoencoders (MIDA)

- The MIDA architecture[1] imputes missing values.
- Based on a **denoising** autoencoder.
- MIDA masker **not suitable** for our problem.

Our Approach: Modify the masker to imitate the pattern of a failing sensor.





[1] Gondara, L., & Wang, K. (2018, June). Mida: Multiple imputation using denoising autoencoders. In Pacific-Asia conference on knowledge discovery and data mining (pp. 260-272). Springer, Cham. Bodyo°

Evaluation : feature reconstruction error



Evaluation : feature distribution



Evaluation : blood pressure classification

- Dataset: 329 samples with 24 features.
- Data from at least one of the sensors is missing for 48 samples.
- Use case: assess if imputation improves the binary classification of BP categories according to 2 categories.

	Accuracy	F1-score	Precision	Sensitivity	
None	0.67	0.65	0.62	0.69	-
Mean	0.64	0.67	0.59	0.77	
 Our method	0.71	0.71	0.65	0.77	
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Limitations of imputation

- There may be additional information, not collected by the sensors.
- In our dataset, only **105 samples** (out of 329) have no missing values.
- Imputation of poorly represented information can introduce **significant biases** in the learning process.





Set approach to learn with missing values





Set models

- Most classical machine learning models require **fixeddimensional** inputs.
- Sets allow to overcome this limitation.
- Good alternative to learn with missing values.





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Furthermore, attention-based models perform a weighted summation of a set of features (Vaswani et al., 2017; Lee et al., 2018). Hence, understanding the mathematical prop-MOGES based models is valuable both in terms of setstructured applications as well as better understanding the

 ϕ and ρ can be implemented by e.g. near a net ϕ on b.

- · Idea: capabperes utation invariant attention taxet shodels.
- Permutanigno invariance himseling liffedelst insthe ing derived of its inputnetworks and Gaussian processes, are fundamentally based on vector inputs¹ rather than set inputs. In order to adapt The these models for use owith sets, we must enforce the property able uniofrpre imutaltiont invationiffet ine.atheuoctipet of the Acdel mast R in taking ^{such that} hange if the inputs are reordered. Multiple authors, in-cluding Ravanbakhsh et al. (2015), Zaheer et al. (2017) and ent neural Sutskever Qi et al. (2017a), have considered enforcing this property e the stateal., **EUB** ECOM a technique which we term sum-decomposition, illes-od vo trated in Figure 1. Mathematically speaking, we say that a uts in the function f defined on sets of size M is sum-decomposable anbakhsh *via* Z if there are functions $\phi : \mathbb{R} \to Z$ and $\rho : Z \to \mathbb{R}$ such Lee et al., 1 12

Deep Sets architecture





[2] Zaheer, M., Kottur, S., Ravanbakhsh, S., Poczos, B., Salakhutdinov, R. R., & Smola, A. J. (2017). Deep sets. Advances in neural information processing systems, 30.

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Our approach

- Each input vector X_i is **encoded as a set** of permutation invariant observations x_j .
- Each x_j is represented as a **tuple** (v_j, m_j) such that :

 $X_i:=\{(v_1,\ m_1),...,(v_p,\ m_p)\}$

• The whole dataset can then be described as:

 $D:=\{(X_1,\ y_1),...,(X_n,\ y_n)\}$

Our Approach: Allows us to deal with missing values.



Paper in writting.



Evaluation: diabetes classification

- The **Pima Indians Diabetes**[3] database is composed of **768 samples** and **8 features**.
- Up to 374 samples have missing values across 5 features.



Evaluation : benchmark

- **Benchmark**: Logistic regression, Random Forests and Gradient Boosting.
- Missing values need to be **imputed** first for the benchmark.

	Accuracy	F1-score	Precision	Sensitivity
Mean imp. + LR	0.753	0.61	0.70	0.52
Mean imp. + RF	0.772	0.65	0.71	0.59
Mean imp. + GB	0.727	0.59	0.62	0.56
Our method	0.792	0.71	0.68	0.74





Concluding remarks

- The problem of missing values is a **particularly sensitive** issue in the medical field.
- We proposed two **simple** yet **robust** models that yield good performances.
- Imputation methods should be used **sparingly** to avoid biases in the learning.





Ongoing work

- Develop a way to compute a **weighted aggregation**.
- Test the method on the AiPod data.
- Investigate the **combination** of the two approaches.









Thank you!

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