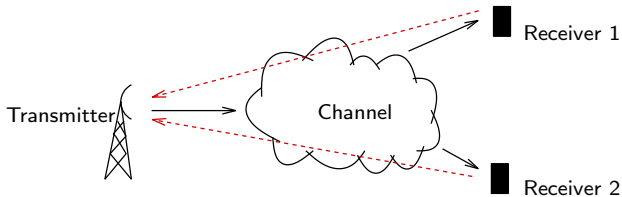


# Memoryless Broadcast Channels with Feedback

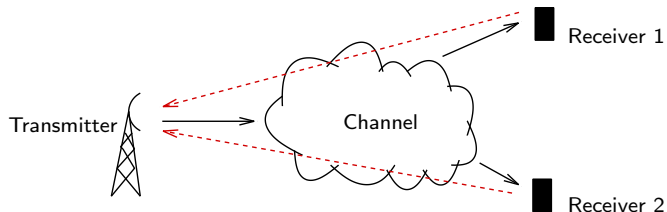


Michèle Wigger ([michele.wigger@telecom-paristech.fr](mailto:michele.wigger@telecom-paristech.fr))

joint work with Michael Gastpar, Amos Lapidoth, Ofer Shayevitz

Eurecom, 1 July 2010, Nice, France

# Broadcast Channels (BCs) with Feedback



- ▶ Two models:
  - ▶ Fading BC with memory and "state-feedback"
  - ▶ Memoryless BC with output feedback

# In this Talk: Memoryless BCs with Output Feedback

## Discrete Memoryless BCs

- ▶ Propose new coding scheme
- ▶ For some channels our scheme
  - ▶ Is optimal (in terms of rate)
  - ▶ Improves on optimal no-feedback scheme, even with noisy feedback

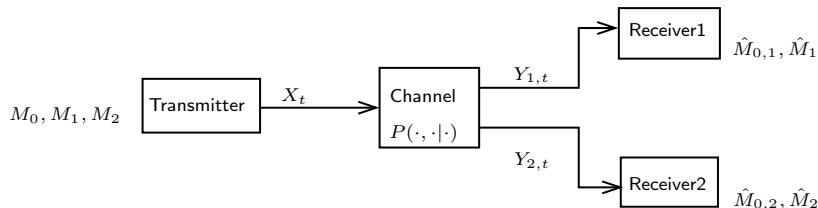
## Scalar Gaussian BCs

- ▶ Feedback can double achievable throughput (sum-capacity)
- ▶ Feedback-gain susceptible to noise on feedback links

Part I:

Discrete Memoryless BCs

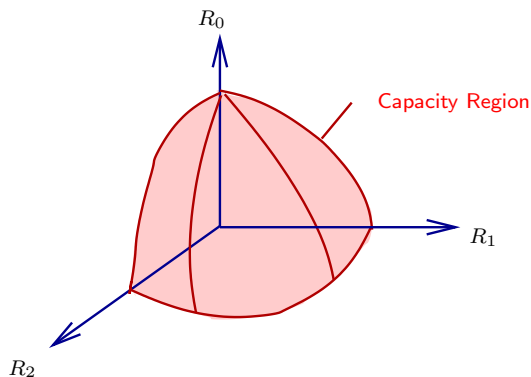
## Discrete Memoryless BC without Feedback



- ▶ Rx 1 wants to learn Messages  $M_0, M_1$ ; and Rx 2 Messages  $M_0, M_2$
- ▶ Inputs  $X_t = f_t(M_0, M_1, M_2)$
- ▶ Finite input and output alphabets  $\mathcal{X}, \mathcal{Y}_1, \mathcal{Y}_2$
- ▶ Channel memoryless  $(Y_{1,t}, Y_{2,t}) \text{---} X_t \text{---} (X^{t-1}, Y_1^{t-1}, Y_2^{t-2})$
- ▶ Channel law:  $P(y_1, y_2 | x)$  of observing  $y_1$  and  $y_2$  given input  $x$

## Capacity Region/Sum-Capacity

- ▶ Rates of communication  $R_0, R_1, R_2 \geq 0$
- ▶ **Capacity region  $\mathcal{C}$** : Set of  $(R_0, R_1, R_2)$  s.t.  $p(\text{error})$  arbitrarily small
- ▶ **Sum-capacity  $C_{\text{Sum}}$** : maximum throughput  $(R_0 + R_1 + R_2)$  s.t.  $p(\text{error})$  arbitrarily small



# Capacity of discrete memoryless BC without Feedback

- ▶ Capacity region in general unknown
- ▶ Outer bound on capacity: augmented cutset bound
- ▶ Achievable region [Marton'79]:

$(R_0, R_1, R_2)$  achievable if:

$$R_0 < \min_i I(U_0; Y_i)$$

$$R_0 + R_1 < I(U_0, U_1; Y_1)$$

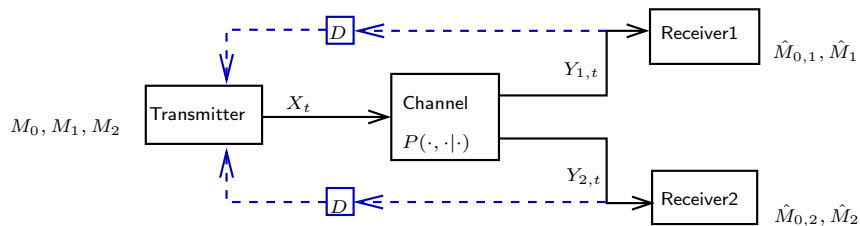
$$R_0 + R_2 < I(U_0, U_2; Y_2)$$

$$R_0 + R_1 + R_2 < I(U_1; Y_1|U_0) + I(U_2; Y_2|U_0) \\ + \min_i I(U_0; Y_i) - I(U_1; U_2|U_0)$$

for some  $(U_0, U_1, U_2)$  forming Markov chain  $(U_0, U_1, U_2) - X - (Y_1, Y_2)$

- ▶ For some channels: Marton's region and augmented cutset bound tight

## Noise-Free Feedback

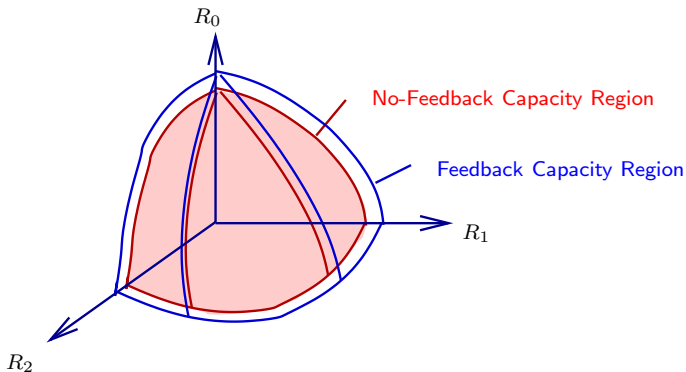


- ▶ Transmitter causally observes channel outputs
- ▶ Can compute inputs as:

$$X_t = f_t(M_0, M_1, M_2, Y_1^{t-1}, Y_2^{t-1})$$



# Does Noise-Free Feedback Increase Capacity?



$$C_{BC, \text{NoFB}} = C_{BC, \text{FB}} \quad \text{or} \quad C_{BC, \text{NoFB}} \subsetneq C_{BC, \text{FB}}?$$

- ▶ Recall: For memoryless point-to-point channels feedback does NOT increase capacity

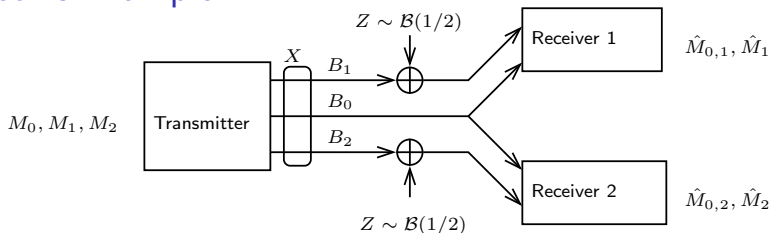
# Previous Results on Capacity of DMBCs with Feedback

- ▶ El Gamal'78: **No feedback-gain** for physically degraded BCs
- ▶ Dueck'80, Kramer'00: **Feedback-gain** for specific discrete memoryless BCs
- ▶ Kramer'00: Multi-letter achievable region for general channels
- ▶ Capacity region not known in general

## In this talk

Single-letter achievable region for general channels

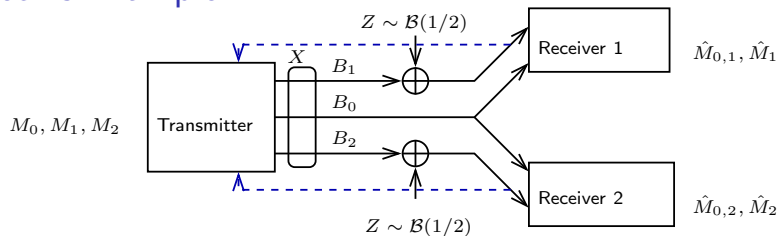
## Dueck's Example



Without feedback:

- ▶ Top and bottom links useless
- ▶ No-feedback capacity:  $0 \leq R_0 + R_1 + R_2 \leq 1$

# Dueck's Example



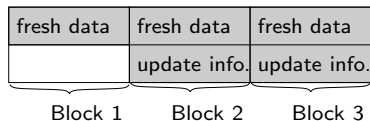
Noise-free feedback:

- ▶ Transmitter learns noise and sends  $B_{0,t} = Z_{t-1}$
- ▶ Feedback capacity:  $0 \leq R_0 + R_1, R_0 + R_2 \leq 1$

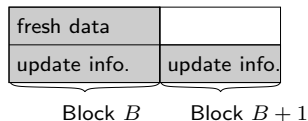
## Intuition why feedback helps

- ▶ "Actions" of channels  $X \rightarrow Y_1$  and  $X \rightarrow Y_2$  correlated
- ▶ Can send information useful to both receivers

# Our Coding Scheme

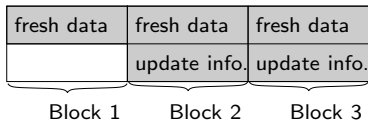


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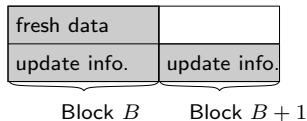


- ▶ Block-Markov strategy
- ▶ Update info. about previous channel "actions" learned via feedback
- ▶ Fresh data/update info. sent with Marton's no-fb scheme
- ▶ Backward decoding:
  1. Block- $b$  outputs improved with block- $(b + 1)$  update info.
  2. Marton-decoding based on improved outputs

# Our Coding Scheme



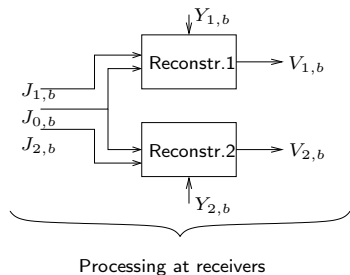
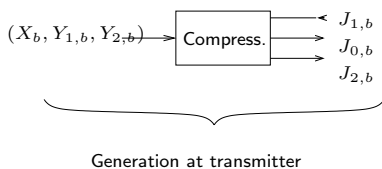
...



- ▶ Block-Markov strategy
- ▶ Update info. about previous channel "actions" learned via feedback
- ▶ Fresh data/update info. sent with Marton's no-fb scheme
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# Update info.: Lossy GW-Compression of Channel Actions

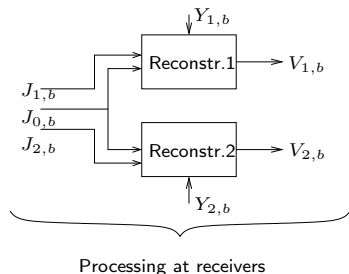
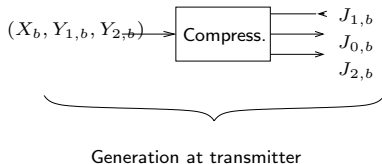
Update info sent in block  $(b + 1)$ :



- ▶  $V_{1,b}, V_{2,b}$ : lossy reconstructions of channel "actions"
- ▶ Indices  $(J_{0,b}, J_{1,b}, J_{2,b})$  describe lossy compression of  $(X_b, Y_{1,b}, Y_{2,b})$
- ▶ Goal:  $(V_{i,b}, X_b, Y_{1,b}, Y_{2,b})$  jointly typical  $\sim P_{V_i, X, Y_1, Y_2}$
- ▶ Improved block- $b$  outputs at Rx  $i$ :  $(V_{i,b}, Y_{i,b})$

# Update info.: Lossy GW-Compression of Channel Actions

Update info sent in block  $(b + 1)$ :



- ▶  $V_{1,b}, V_{2,b}$ : lossy reconstructions of channel "actions"
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- ▶ Improved block- $b$  outputs at Rx  $i$ :  $(V_{i,b}, Y_{i,b})$

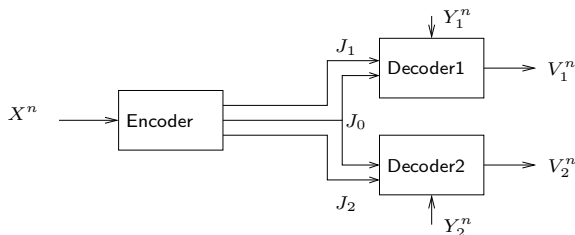
Due to side-info, even independent  $V_{1,b}$  and  $V_{2,b}$  have interesting  $J_0$



# Lossy Gray-Wyner Source Coding with Side-Info.

Given:  $P_{XY_1Y_2}P_{V_1V_2|X}$ ;  $(X^n, Y_1^n, Y_2^n) \sim \text{IID } P_{XY_1Y_2}$

Goal:  $V_i^n$  jointly typical with  $X^n$  according to  $P_{X,V_i}$



A triplet  $(R_0, R_1, R_2)$  is achievable, if

$$R_0 > \max_i I(X; V_0 | Y_i),$$

$$R_1 > I(X; V_1 | V_0, Y_1)$$

$$R_2 > I(X; V_2 | V_0, Y_2)$$

for some  $V_0$  s.t.  $(V_0, V_1, V_2) \text{---} X \text{---} (Y_1, Y_2)$  forms a Markov chain.

# Our Achievable Region for the DMBC with Feedback

## Theorem

Nonnegative triplet  $(R_0, R_1, R_2)$  achievable if,

$$R_0 \leq \min_i I(U_0; Y_i, V_i) - \max_i I(V_0; X, Y_1, Y_2 | Y_i)$$

$$R_0 + R_1 \leq I(U_0, U_1; Y_1, V_1) - I(X, Y_2; V_1 | V_0, Y_1) - \max_i I(V_0; X, Y_1, Y_2 | Y_i)$$

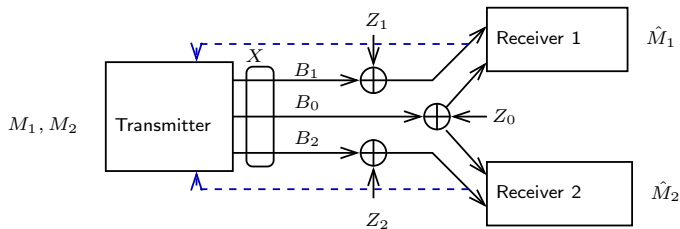
$$R_0 + R_2 \leq I(U_0, U_2; Y_2, V_2) - I(X, Y_1; V_2 | V_0, Y_2) - \max_i I(V_0; X, Y_1, Y_2 | Y_i)$$

$$R_0 + R_1 + R_2 \leq I(U_1; Y_1, V_1 | U_0) + I(U_2; Y_2, V_2 | U_0) + \min_i I(U_0; Y_i, V_i) \\ - I(U_1; U_2 | U_0) - I(X, Y_1, Y_2; V_1 | V_0, Y_1) - I(X, Y_1, Y_2; V_2 | V_0, Y_2) \\ - \max_i I(V_0; X, Y_1, Y_2 | Y_i)$$

for some  $(U_0, U_1, U_2, V_0, V_1, V_2)$  such that

$$(U_0, U_1, U_2) \text{---} X \text{---} (Y_1, Y_2) \\ (V_0, V_1, V_2) \text{---} (X, Y_1, Y_2) \text{---} (U_0, U_1, U_2)$$

# Capacity of Generalized Dueck-Example with Noise-Free Fb



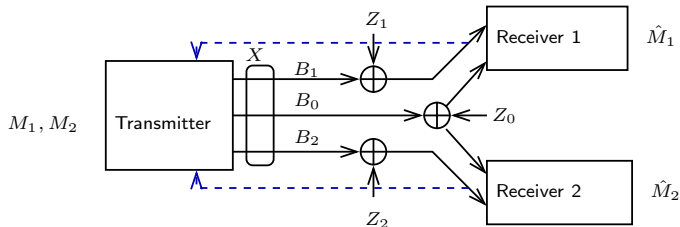
- ▶  $B_0, B_1, B_2, Z_0, Z_1, Z_2$  binary
- ▶ Assumption:  $H(Z_0, Z_1) \leq 1$  and  $H(Z_0, Z_2) \leq 1$
- ▶ **No feedback capacity:** all pairs  $(R_1, R_2)$  s.t.

$$R_1 \leq 2 - H(Z_0, Z_1)$$

$$R_2 \leq 2 - H(Z_0, Z_2)$$

$$R_1 + R_2 \leq 3 - H(Z_0, Z_1, Z_2) - I(Z_1; Z_2|Z_0).$$

# Capacity of Generalized Dueck-Example with Noise-Free Fb



- ▶  $B_0, B_1, B_2, Z_0, Z_1, Z_2$  binary
- ▶ Assumption:  $H(Z_0, Z_1) \leq 1$  and  $H(Z_0, Z_2) \leq 1$
- ▶ **Noise-free feedback capacity:** all pairs  $(R_1, R_2)$  s.t.

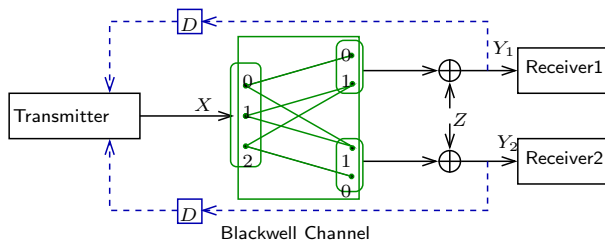
$$R_1 \leq 2 - H(Z_0, Z_1)$$

$$R_2 \leq 2 - H(Z_0, Z_2)$$

$$R_1 + R_2 \leq 3 - H(Z_0, Z_1, Z_2)$$

→ feedback helps iff  $Z_1 \text{---} Z_0 \text{---} Z_2$  does NOT hold!

## Another Example: Noisy Blackwell Channel



- ▶ Noise  $Z \sim \mathcal{B}(p)$
- ▶ Both channel outputs corrupted by same noise (for simplicity)

# Our Achievable Region for Noisy Blackwell Channel

$(R_0, R_1, R_2)$  achievable if for some  $\alpha, \beta \in [0, 1]$ :

$$R_0 \leq h_b \left( \frac{\alpha + \beta}{2} \right) - \frac{1}{2}(h_b(\alpha) + h_b(\beta)) - \lambda(p, \alpha, \beta)$$

$$R_0 + R_1 \leq h_b \left( \frac{\alpha + \beta}{2} \right) - \lambda(p, \alpha, \beta)$$

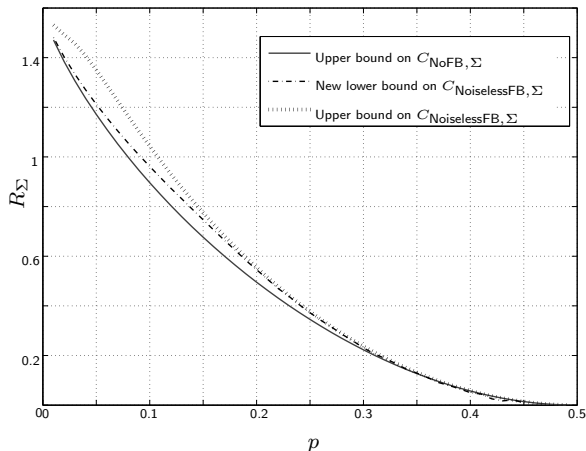
$$R_0 + R_2 \leq h_b \left( \frac{\alpha + \beta}{2} \right) - \lambda(p, \alpha, \beta)$$

$$R_0 + R_1 + R_2 \leq h_b \left( \frac{\alpha + \beta}{2} \right) + \frac{1 - \beta}{2} h_b \left( \frac{\alpha}{1 - \beta} \right) \\ + \frac{1 - \alpha}{2} h_b \left( \frac{\beta}{1 - \alpha} \right) - \lambda(p, \alpha, \beta)$$

where

$$\lambda(p, q, \alpha, \beta) \triangleq h_b(p) + h_b \left( \frac{\alpha + \beta}{2} \right) - h_b \left( \left( \frac{\alpha + \beta}{2} \right) \star p \right)$$

# Sum-Capacity of Noisy Blackwell Chan. with Noise-free Fb



## Usefulness of Feedback

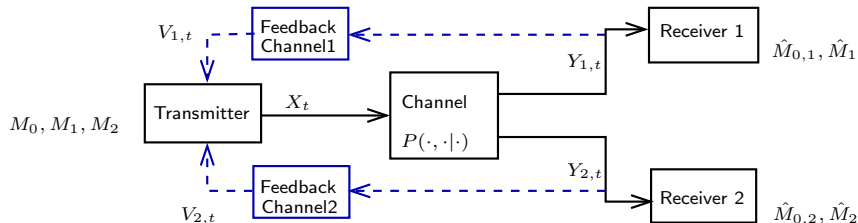
- For most values  $p$  noise-free feedback beneficial

## Improved Coding Scheme

- ▶ *Channels of interest* in Marton's scheme:  $(U_0, U_1) \rightarrow Y_1$  and  $(U_0, U_2) \rightarrow Y_2$
- ▶ Update info: lossy compression of these channel "actions", i.e., of  $(U_0, U_1, U_2, Y_1, Y_2)$
- ▶ At least as good as before. Better?

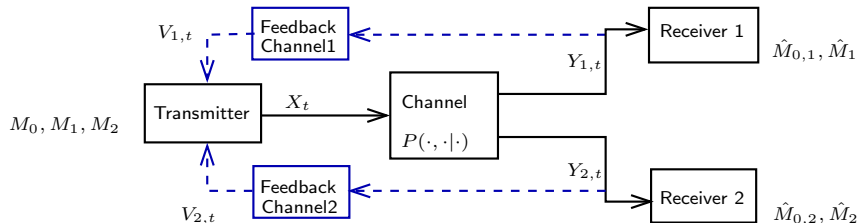


## Noisy Feedback



- ▶ Noisy Feedback  $(V_{1,t}, V_{2,t}) \leftarrow (Y_{1,t}, Y_{2,t}) \leftarrow (X^t, Y_1^{t-1}, Y_2^{t-1})$
- ▶ E.g.,  $V_{1,t} = Y_{1,t} + W_{1,t}$  and  $V_{2,t} = Y_{2,t} + W_{2,t}$
- ▶ Inputs:  $X_t = f_t(M_0, M_1, M_2, V_1^{t-1}, V_2^{t-1})$

## Noisy Feedback



Our scheme still works:

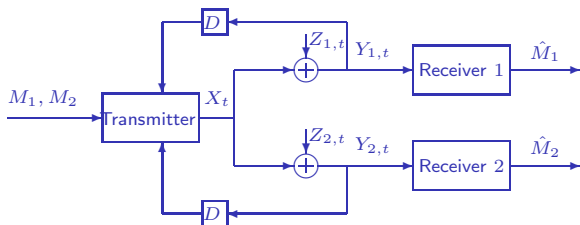
Exchange  $(Y_1, Y_2)$  by  $(V_1, V_2)$  when compressing channel-"actions"

- ▶ Noisy Blackwell channel: even with noisy feedback our scheme improves on no-feedback

## Part II:

# Scalar Gaussian Memoryless BC

# Scalar Gaussian Broadcast Channel



▶  $X_t, Y_{1,t}, Y_{2,t} \in \mathbb{R}$

▶  $Y_{\nu,t} = X_t + Z_{\nu,t}, \quad \begin{pmatrix} Z_{1,t} \\ Z_{2,t} \end{pmatrix} \sim \mathcal{N}\left(\mathbf{0}, \begin{pmatrix} N_1 & \rho_z \sqrt{N_1 N_2} \\ \rho_z \sqrt{N_1 N_2} & N_2 \end{pmatrix}\right)$

▶ Noise correlation caused by interference

▶ Only private messages  $M_1$  and  $M_2$

# No Feedback

## Capacity Region when $N_1 \leq N_2$

All pairs  $(R_1, R_2)$  such that for some  $\alpha \in [0, 1]$ :

$$R_1 \leq \frac{1}{2} \log \left( 1 + \frac{\alpha P}{N_1} \right)$$
$$R_2 \leq \frac{1}{2} \log \left( 1 + \frac{(1 - \alpha)P}{\alpha P + N_2} \right).$$

- ▶ Achieved by superposition coding — a special case of Marton's scheme
- ▶ Capacity region independent of noise-correlation  $\rho_z$ !

# Noise-Free Feedback

- ▶ Outer bound [Ozarow/Leung'84]
- ▶ Achievable regions [Ozarow/Leung'84] and [Bhaskaran'06]
- ▶ Capacity region not known, seems difficult

## Other Questions:

- ▶ Can feedback *significantly* increase capacity?
- ▶ Feedback-gains in the high-SNR regime?

# High-SNR Asymptotics: Degrees of Freedom

- ▶ Degrees of freedom:

$$\eta \triangleq \overline{\lim}_{P \rightarrow \infty} \frac{C_{\text{Sum}}(P, N_1, N_2)}{1/2 \log(P)}$$

- ▶ Classical result: MIMO Gaussian channel with **independent** noises

$$\begin{aligned} \eta_{\text{MIMO}} &= \text{rank}(\text{channel matrix}) \\ &\leq \min\{\#\text{tx-antennas}, \#\text{rx-antennas}\} \end{aligned}$$

**Holds also with feedback!**

- ▶ Intuition:  $\eta_{\text{MIMO}} = \#$  interference-free Gaussian channels in system

## Degrees of Freedom of BC without Feedback

- ▶ Degrees of freedom:  $\eta_{\text{BC}} \triangleq \lim_{P \rightarrow \infty} \frac{C_{\text{BC,Sum}}(P, \sigma_1^2, \sigma_2^2, \rho_z)}{\frac{1}{2} \log(P)} = 1$
- ▶ Degrees of freedom independent of  $\rho_z$
- ▶ Only 1 "interference-free" link  $\rightarrow$  receivers share 1 Gaussian channel



# Capacity Results for Memoryless Networks at High SNR

- ▶ Memoryless single-user channel: no capacity gain with feedback (Shannon)
- ▶ Gaussian single-user channel with memory: at most  $1/2$  bit (Cover/Pombra)
- ▶ Two-user Gaussian MAC with memory: at most  $1/2$  bit (Thomas)
- ▶ For regular/non-regular fading channels: no change in high-SNR first order asymptotics (Lapidoth/Moser)

→ For these settings feedback insignificant at high SNR

## 2 Degrees of Freedom Possible with 1 Transmit-Antenna

### Theorem

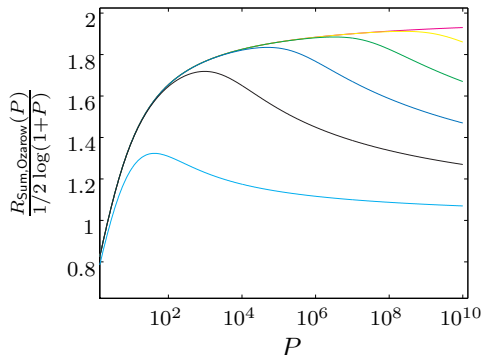
Degrees of freedom of *scalar* Gaussian BC with noise-free feedback

$$\eta_{\text{BCFB}} = \begin{cases} 1, & |\rho_z| < 1, \\ 2, & \rho_z = -1. \end{cases}$$

- ▶ For  $\rho_z = -1$ :
  - ▶ Feedback doubles high-SNR capacity
  - ▶ At high SNR: as if transmitter had 2 separate links to receivers
  - ▶  $\eta_{\text{BCFB}}$  can be larger than  $\#$  tx-antennas

## Correlation $\rho_z = -1$ ?

- ▶ Correlation  $\rho_z = -1$  unlikely. Thermal noise at receivers!
- ▶ For finite powers: what if there is only **small** thermal noise?



Sum-rates for  $\rho_z = -0.9, -0.999, -0.99999, -0.9999999, -0.999999999, -1$ .

## Feedback Gains for $\rho_z \neq -1$

- ▶ For  $P \gg 1$  and  $\rho_z \approx 1 - \frac{1}{P^\alpha}$  sum-capacity multiplied by  $(1 + \alpha)$ ,  
 $\alpha \in [0, 1]$

### Theorem

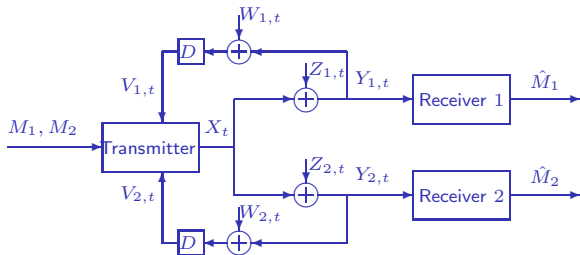
For  $\rho_z(P)$  depending on power  $P$ :

$$\eta_{\text{BCFB}} = \min \left\{ 2, 1 + \overline{\lim}_{P \rightarrow \infty} \frac{-\log(1 + \rho_z(P))}{\log(P)} \right\}.$$

Thus, if  $\rho_z(P) \sim (-1 + P^{-\alpha})$

$$\Rightarrow \eta_{\text{BCFB}} = (1 + \alpha), \quad \alpha \in [0, 1].$$

# Noisy Feedback



- $V_{\nu,t} = Y_{\nu,t} + W_{\nu,t}, \quad \left\{ \begin{pmatrix} W_{1,t} \\ W_{2,t} \end{pmatrix} \right\} \text{ IID } \sim \mathcal{N}\left(\mathbf{0}, \begin{pmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{pmatrix}\right)$
- $\{(W_{1,t}, W_{2,t})\}$  independent of  $\{(Z_{1,t}, Z_{2,t})\}$
- Transmitter observes noisy feedback:  $X_t = f_t(M_1, M_2, V_1^{t-1}, V_2^{t-1})$

# Collapse in Degrees of Freedom with Noisy Feedback

## Theorem

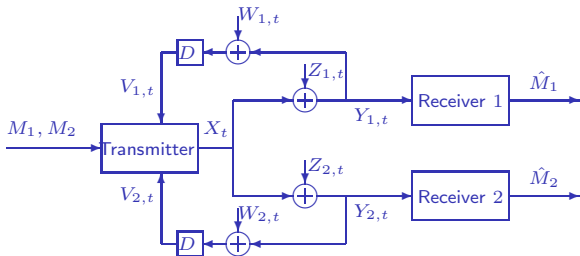
*Degrees of freedom:*

$$\eta_{\text{BC,NoisyFB}} = 1, \quad \text{for all } \rho_z \in [-1, 1],$$

*when  $\sigma_1^2, \sigma_2^2$  fixed and positive.*

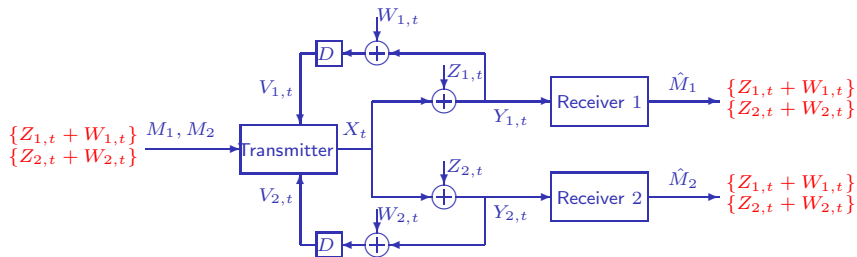
- ▶ Noise on feedback causes degrees of freedom to collapse!
- ▶ Promised gain very sensitive to feedback noise
- ▶ Engineering intuition “ $\eta \leq \min\{\#\text{tx-antennas}, \text{rx-antennas}\}$ ” OK!

# Proof Idea why Degrees of Freedom Collapse



Proof idea: 3 transformations that don't decrease capacity

# Proof Idea why Degrees of Freedom Collapse

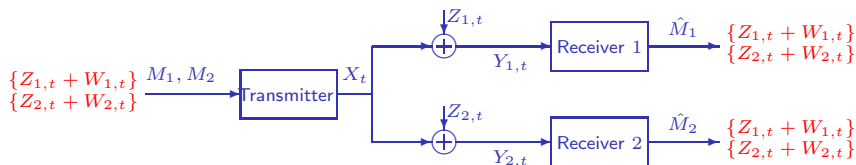


Proof idea: 3 transformations that don't decrease capacity

1. Genie info  $\{(Z_{1,t} + W_{1,t}, Z_{2,t} + W_{2,t})\}$  to tx and rxs  $\rightarrow$  feedback useless



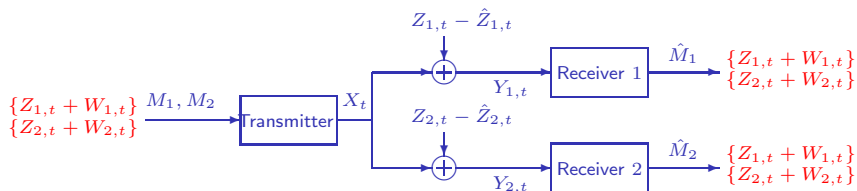
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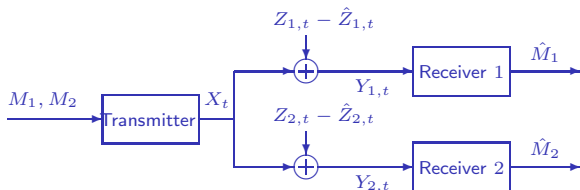
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4. Resulting channel without fb/genie info: 1 degree of freedom

# Summary

## Discrete Memoryless BCs:

- ▶ New coding scheme for DMBC with feedback and new achievable region
- ▶ Simple example where our scheme yields noise-free feedback-capacity
- ▶ Noisy Blackwell channel: scheme improves on no-feedback capacity; even for noisy feedback

## Scalar Gaussian BC:

- ▶ Noise-free feedback offers significant gains (doubles sum-capacity)
- ▶ Noise-free feedback: 2 degrees of freedom achievable with 1 tx-antenna ( $\rho_z \approx -1$ )
- ▶ Gains collapse when feedback noisy